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CIRCLE	LECTURE AND LAB SECTIONS:	Т	his	exa	m l	has	11	pro	bleı	ms o	on 1	0 pa	ages
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$\mathbf{L}\mathbf{A}$	B: 003 Th 1:30 004 Th 12:30 005 Th 2:30	006 '	Th 1	0:30) 0	07 1	W 1	0:30	0	08 V	V 9:3	30	
NO CAL	CULATORS, NOTES OR OTHER AIDS	•											
* /	ach of the following, circle T if the statement is not guess: wrong answers will receive -2 man If A is a $n \times n$ matrix, then $A - A^T$ is skew-s	· ks . ymme	tric.			eircl	e F	if it	can	be	false	е. Т]
	Solution: True: $(A - A^T)^T = A^T - (A^T)^T = A^T$												
(b)						t.	Т	F					
Solution: False: rather, they must be linearly independent. (c) If A is an invertible matrix, then the system $A\mathbf{x} = \mathbf{b}$ has a solution for every b .						\mathbf{T}	F						
(c) If A is an invertible matrix, then the system $A\mathbf{x} = \mathbf{b}$ has a solution for every \mathbf{b} . Solution: True: solution is $\mathbf{x} = A^{-1}\mathbf{b}$.						T	г						
(d)	If A is an invertible matrix and two rows are	interch	nang	ed.									
	then the resulting matrix is invertible.		. 0)								\mathbf{T}	F
	Solution: True: exchanging rows changes determ	inant b	yas	ign.									
(e)	If A and B are $n \times n$ matrices, then $\det(A +$	B) = c	let(⊿	(4) +	det	(B)						\mathbf{T}	\mathbf{F}
	Solution: False: however, $det(AB) = det(A) det(AB)$	<i>B</i>).											

- (f) If λ = 0 is an eigenvalue of A, then A is invertible. T F Solution: False: if 0 is an eigenvalue, determinant is zero.
 (g) If A is a 3 × 4 matrix, then the system Ax = 0 has infinitely many solutions. T F
- (g) If A is a 3×4 matrix, then the system $A\mathbf{x} = \mathbf{0}$ has infinitely many solutions. **T** Solution: True: after row-reducing, at most three leading ones, but four columns.

For all remaining problems, you must SHOW ALL OF YOUR WORK and EXPLAIN FULLY to receive full credit.

(3 pts) **2.** Find the area of the triangle with vertices at (1,1), (4,6) and (0,3).

Solution: Let $\mathbf{v} = (4-1, 6-1)$ and $\mathbf{u} = (0-1, 3-1)$ be the vectors along the two sides of the triangle that meet at the point (1,1). Then $\mathbf{v} = (3,5)$ and $\mathbf{u} = (-1,2)$. The triangle has half the area of the parallelogram formed by \mathbf{u} and \mathbf{v} , so its area is

$$= \frac{1}{2} \left| \det \begin{bmatrix} 3 & -1 \\ 5 & 2 \end{bmatrix} \right|$$

= $(6+5)/2$
= $11/2.$

3. Let $\mathbf{u} = (3, 2, 1)$ and $\mathbf{v} = (1, 2, 3)$.

(4 pts) (a) Evaluate $\|\mathbf{u}\|$, $3\mathbf{u} - \mathbf{v}$, $\mathbf{u} \cdot \mathbf{v}$ and $\mathbf{u} \times \mathbf{v}$.

Solution:

$$\|\mathbf{u}\| = \sqrt{3^2 + 2^2 + 1^2}$$

= $\sqrt{14}$;
 $3\mathbf{u} - \mathbf{v} = 3(3, 2, 1) - (1, 2, 3)$
= $(8, 4, 0)$;
 $\mathbf{u} \cdot \mathbf{v} = 3 \cdot 1 + 2 \cdot 2 + 1 \cdot 3$
= 10 ;
 $\mathbf{u} \times \mathbf{v} = (2 \cdot 3 - 2 \cdot 1, -(3 \cdot 3 - 1 \cdot 1), (3 \cdot 2 - 2 \cdot 1))$
= $(4, -8, 4)$

(3 pts) (b) Find all scalars s and t for which $s\mathbf{u} + t\mathbf{v}$ is orthogonal to the vector (1, -1, 1). Solution: The vector $s\mathbf{u} + t\mathbf{v}$ is orthogonal to (1, -1, 1) if and only if $(3s + t, 2s + 2t, s + 3t) \cdot (1, -1, 1) = 0$. That is,

$$0 = 3s + t - (2s + 2t) + s + 3t$$

= 2s + 2t,

so the vectors are orthogonal for all scalars t and s = -t.

(4 pts) **4.** (a) Use row operations to put the following matrix into reduced row echelon form. You must show the intermediate matrices, but you don't have to describe the row operations you used.

	$A = \begin{bmatrix} 1 & 0 & 3 & 0 & 1 \\ 1 & -1 & 5 & -1 & 2 \\ -2 & 1 & -8 & 1 & -3 \end{bmatrix}$
Solution: Row-reduce to	$\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$
then	$\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$
then	$\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$

(3 pts) (b) Using the previous part, write down the general solution to the following system in parametric form.

x + 3z = 1 x - y + 5z - w = 2-2x + y - 8z + w = -3

Solution: The calculation above row-reduced the augmented matrix for this system. So we see that z and w are free variables: let z = s and w = t, so that the general solution is

$$x = 1 - 3s$$

$$y = -1 + 2s - t$$

$$z = s$$

$$w = t.$$

5. Dan was solving a system of equations in x, y and z. He found the reduced row-echelon form of his augmented matrix was

1	0	-1	1	
0	1	2	-2	
0	0	0	$\begin{array}{c}1\\-2\\0\end{array}$	

 (3 pts)
 (a) He lost a page of his notes and could not remember what the original system of equations was. However, he remembers that he used only two row operations: first he subtracted row one from row three, and then he added three times row two to row three. What was the original system of equations?

Solution: We can undo the operations by first subtracting three times row 2 from row 3 to get

	$\left[\begin{array}{c}1\\0\\0\end{array}\right]$	$\begin{array}{c} 0 \\ 1 \\ -3 \end{array}$	$-1 \\ 2 \\ -6$	$\left \begin{array}{c}1\\-2\\6\end{array}\right].$
Then add row 1 to row 3:	$\left[\begin{array}{c}1\\0\\1\end{array}\right]$	$0 \\ 1 \\ -3$	$-1 \\ 2 \\ -7$	$\left \begin{array}{c}1\\-2\\7\end{array}\right].$
This corresponds to the system of equation	ns			

This corresponds to the system of equations

(3 pts) (b) Does this system of equations have any solutions? If so, state how many solutions it has and say whether the solutions form a point, a line, a plane or all of R^3 .

Solution: Yes: the row-reduced form had a full row of zeros, so the system is consistent. There is one free variable, so the solutions from a line in \mathbb{R}^3 .

(4 pts) **6.** Compute the inverse of the matrix
$$A = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 6 & 2 \\ 0 & 2 & 1 \end{bmatrix}$$
.

Solution: Row-reduce $(A|I_3)$:

$$\begin{bmatrix} 1 & 2 & 0 & | & 1 & 0 & 0 \\ 2 & 6 & 2 & | & 0 & 1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & | & 1 & 0 & 0 \\ 0 & 2 & 2 & | & -2 & 1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -1 & 1/2 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -1 & 1/2 & 0 \\ 0 & 0 & -1 & | & 2 & -1 & 1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -1 & 1/2 & 0 \\ 0 & 0 & -1 & | & 2 & -1 & 1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & 1 & -1/2 & 1 \\ 0 & 0 & -1 & | & 2 & -1 & 1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 0 & 0 & | & -1 & 1 & -2 \\ 0 & 1 & 0 & | & 1 & -1/2 & 1 \\ 0 & 0 & 1 & | & -2 & 1 & -1 \end{bmatrix}$$

So $A^{-1} = \begin{bmatrix} -1 & 1 & -2 \\ 1 & -1/2 & 1 \\ -2 & 1 & -1 \end{bmatrix}$.

- 7. (a) Does the set of all vectors of the form (0, a, b) with a and b real numbers form a subspace of $\mathbb{R}^{3?}$ (3 pts)Explain fully. Solution: Yes. Since (0,0,0) has this form, the set is nonempty. Now check: if $\mathbf{v} = (0,a,b)$ and $\mathbf{w} = (0,a',b')$, then $\mathbf{v} + \mathbf{w} = (0, a + a', b + b')$, which is again a vector of this form. Second, check that, for any vector **v** of the form $\mathbf{v} = (0, a, b)$ and for any scalar c, $c\mathbf{v} = (0, ca, cb)$ also has a zero in its first coordinate, so it has the same form. (b) Does the set of all vectors of the form (a, b, c) with a, b and c real numbers with $a \ge 0$ form a
- (3 pts)subspace of \mathbb{R}^3 ? Explain fully. Solution: No. In particular, (1,1,1) is in this set, but -(1,1,1) = (-1,-1,-1) is not, so it can't be a subspace.

Note that to show that something is false, you give an explicit counterexample.

8. (a) Use a determinant to find all values of c for which the vectors $\begin{bmatrix} 2 \\ 0 \\ c \end{bmatrix}$, $\begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix}$, $\begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix}$ are linearly (4 pts)

independent. Solution: Since

$$\det \begin{bmatrix} 2 & 1 & -1 \\ 0 & -1 & 3 \\ c & 0 & 1 \end{bmatrix} = 2 \det \begin{bmatrix} -1 & 3 \\ 0 & 1 \end{bmatrix} + c \det \begin{bmatrix} 1 & -1 \\ -1 & 3 \end{bmatrix}$$
$$= -2 + 2c,$$

the determinant of the matrix with the given vectors as columns is nonzero as long as $c \neq 1$. So the vectors are linearly independent if and only if $c \neq 1$.

(b) Compute the volume of the parallelepiped formed by the vectors $\begin{vmatrix} 2\\0\\0\end{vmatrix}$, $\begin{vmatrix} 13\\-1\\0\end{vmatrix}$, $\begin{vmatrix} -3\\25\\1\end{vmatrix}$. (2 pts)

Solution: We know that its volume is the absolute value of the determinant of the matrix with these three columns. The matrix is upper-triangular, so its determinant is the product of the diagonal entries, 2(-1)(1). So the volume is |-2| = 2.

- **9.** Suppose that A and B are 3×3 matrices with det(A) = 3 and det(B) = 2. Compute the following. No justification needed.
- (a) $\det(A^{-1}) = \det(A)^{-1} = 1/3$ (1 pts)
- (b) $\det(2A) = 2^3 \det(A) = 24$ (1 pts)
- (c) $\det(ABA) = \det A \det B \det A = 18$ (1 pts)

(1 pts) (d)
$$\det(B^T) = \det B = 2$$

- (e) $\det(B^3) = \det B^2 = 8$ (1 pts)
 - 10. Suppose that C is a 4×4 matrix with eigenvalues 1, 2, 3 and 4. Compute the following. No justification needed.
- (a) tr(C) = 1 + 2 + 3 + 4 = 10(1 pts)
- (b) $det(C) = 1 \cdot 2 \cdot 3 \cdot 4 = 24$ (1 pts)
- (c) $det(2I_4 C) = 0$ since 2 is an eigenvalue (1 pts)
- (d) $\operatorname{tr}(2I_4 C) = \operatorname{tr}(2I_4) \operatorname{tr}(C) = -2$ (1 pts)

11. Let
$$A = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 0 \\ 0 & 3 & 2 \end{bmatrix}$$
.

(3 pts) (a) Find the characteristic polynomial of A. Solution: The characteristic polynomial is the determinant of $\lambda I_3 - A$, which is

$$\det \begin{bmatrix} \lambda - 1 & 1 & 1 \\ 0 & \lambda - 2 & 0 \\ 0 & -3 & \lambda - 2 \end{bmatrix} = (\lambda - 1) \det \begin{bmatrix} \lambda - 2 & 0 \\ -3 & \lambda - 2 \end{bmatrix}$$
$$= (\lambda - 1)(\lambda - 2)^{2}.$$

- (2 pts) (b) Find the eigenvalues of A and their algebraic multiplicities. Solution: The eigenvalues are the roots of the characteristic polynomial. From above, those are $\lambda = 1$ (with multiplicity 1) and $\lambda = 2$ (with multiplicity two.)
- (3 pts) (c) Find the eigenspace associated to the *smallest* eigenvalue you found. Solution: The least eigenvalue is $\lambda = 1$, and its eigenspace is the set of solutions to $(1 \cdot I_3 - A)\mathbf{x} = \mathbf{0}$. So we row reduce (I - A):

$$I - A = \begin{bmatrix} 0 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & -3 & -1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & -3 & -1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

So the first variable is a free variable, and the general solution has the form $\mathbf{x} = t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ where t is an arbitrary scalar. That is, the eigenspace for the eigenvalue $\lambda = 1$ is the span of the vector $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.