

Math 1600 Lecture 29, Section 2, 14 Nov 2014

Announcements:

Today we finish 4.3 and start 4.4. Continue **reading** Section 4.4 for next class. Work through recommended [homework questions](#).

Final exam: Monday, December 8, 9am to noon. See the [course home page](#) for final exam **conflict** policy. You should **immediately** notify the registrar or your Dean's office (and your instructor) of any conflicts! (Deadline Nov 21.)

Help Centers: Monday-Friday 2:30-6:30 in MC 106.

Question: Can you find a nonzero complex number z such that $z^2 = 0$?

True/False: If z and w are complex numbers in the first quadrant, then so is zw .

Partial review of Appendix C

A **complex number** is a number of the form $a + bi$, where a and b are real numbers and i is a symbol such that $i^2 = -1$.

Addition: $(a + bi) + (c + di) = (a + c) + (b + d)i$, like vector addition.

Multiplication: $(a + bi)(c + di) = (ac - bd) + (ad + bc)i$.

The **conjugate** of $z = a + bi$ is $\bar{z} = a - bi$. Reflection in real axis. We learned the properties of conjugation.

The **absolute value** or **modulus** of $z = a + bi$ is

$$|z| = |a + bi| = \sqrt{a^2 + b^2}, \quad \text{the distance from the origin.}$$

Since $z\bar{z} = |z|^2$, we have that

$$\frac{z\bar{z}}{|z|^2} = 1 \quad \text{so} \quad \frac{1}{z} = \frac{\bar{z}}{|z|^2} \quad (\text{for } z \neq 0)$$

This can be used to divide complex numbers:

$$\frac{w}{z} = \frac{w}{z} \frac{\bar{z}}{\bar{z}} = \frac{w\bar{z}}{|z|^2}.$$

We learned the properties of absolute value. One of them was

$$|wz| = |w||z|.$$

A complex number $z = a + bi$ can also be expressed in **polar coordinates** (r, θ) , where $r = |z| \geq 0$ and θ is such that

$$a = r \cos \theta \quad \text{and} \quad b = r \sin \theta$$

Then

$$z = r \cos \theta + (r \sin \theta)i = r(\cos \theta + i \sin \theta)$$

Let

$$z_1 = r_1(\cos \theta_1 + i \sin \theta_1) \quad \text{and} \quad z_2 = r_2(\cos \theta_2 + i \sin \theta_2).$$

Then

$$\begin{aligned} z_1 z_2 &= r_1 r_2 (\cos \theta_1 + i \sin \theta_1)(\cos \theta_2 + i \sin \theta_2) \\ &= r_1 r_2 [(\cos \theta_1 \cos \theta_2 - \sin \theta_1 \sin \theta_2) + i(\sin \theta_1 \cos \theta_2 + \cos \theta_1 \sin \theta_2)] \\ &= r_1 r_2 [\cos(\theta_1 + \theta_2) + i \sin(\theta_1 + \theta_2)] \end{aligned}$$

So

$$|z_1 z_2| = |z_1||z_2| \quad \text{and} \quad \text{Arg}(z_1 z_2) = \text{Arg } z_1 + \text{Arg } z_2$$

(up to multiples of 2π).

In particular, if $z = r(\cos \theta + i \sin \theta)$, then $z^2 = r^2(\cos(2\theta) + i \sin(2\theta))$. It follows that the two **square roots** of z are

$$\pm \sqrt{r}(\cos(\theta/2) + i(\sin \theta/2))$$

Partial review of Section 4.3

The eigenvalues of a square matrix A can be computed as the **roots** (also called **zeros**) of the **characteristic polynomial**

$$\det(A - \lambda I)$$

If a is a root of a polynomial $f(x)$, then $f(x) = (x - a)g(x)$. Sometimes, a is also a root of $g(x)$. Then $f(x) = (x - a)^2h(x)$. The largest k such that $(x - a)^k$ is a factor of f is called the **multiplicity** of the root a in f .

In the case of an eigenvalue, we call its multiplicity in the characteristic polynomial the **algebraic multiplicity** of this eigenvalue.

Example: Let $f(x) = x^2 - 2x + 1$. Since $f(1) = 1 - 2 + 1 = 0$, 1 is a root of f . And since $f(x) = (x - 1)^2$, 1 has multiplicity 2.

In the case of an eigenvalue, we call its multiplicity in the characteristic polynomial the **algebraic multiplicity** of this eigenvalue.

Newish material

Theorem D.4 (The Fundamental Theorem of Algebra): A polynomial of degree n has at most n distinct roots. **In fact, the sum of the multiplicities is at most n .**

Therefore:

Theorem: An $n \times n$ matrix A has at most n distinct eigenvalues. **In fact, the sum of the algebraic multiplicities is at most n .**

Complex eigenvalues and eigenvectors

This material isn't covered in detail in the text.

Example 4.7: Find the eigenvalues of $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ (a) over \mathbb{R} and (b) over \mathbb{C} .

Solution: We must solve

$$0 = \det(A - \lambda I) = \det \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix} = \lambda^2 + 1.$$

(a) Over \mathbb{R} , there are no solutions, so A has no real eigenvalues. This is why the Theorem above says "at most n ". (This matrix represents rotation by 90 degrees, and we also saw geometrically that it has no real eigenvectors.)

(b) Over \mathbb{C} , the solutions are $\lambda = i$ and $\lambda = -i$. For example, the eigenvectors for $\lambda = i$ are the nonzero **complex** multiples of $\begin{bmatrix} i \\ 1 \end{bmatrix}$, since

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} i \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ i \end{bmatrix} = i \begin{bmatrix} i \\ 1 \end{bmatrix}.$$

In fact, $\lambda^2 + 1 = (\lambda - i)(\lambda + i)$, so each of these eigenvalues has algebraic multiplicity 1. So in this case the sum of the algebraic multiplicities is **exactly** 2.

The Fundamental Theorem of Algebra can be extended to say:

Theorem D.4 (The Fundamental Theorem of Algebra): A polynomial of degree n has at most n distinct **complex** roots. In fact, the sum of their multiplicities is **exactly** n .

Another way to put it is that over the complex numbers, every polynomial factors into **linear** factors.

Real matrices

Notice that i and $-i$ are complex conjugates of each other.

If the matrix A has only real entries, then the characteristic polynomial has real coefficients. Say it is

$$\det(A - \lambda I) = a_n \lambda^n + a_{n-1} \lambda^{n-1} + \cdots + a_1 \lambda + a_0,$$

with all of the a_i 's real numbers. If z is an eigenvalue, then so is its complex

conjugate \bar{z} , because

$$\begin{aligned} a_n \bar{z}^n + a_{n-1} \bar{z}^{n-1} + \cdots + a_1 \bar{z} + a_0 \\ = \overline{a_n z^n + a_{n-1} z^{n-1} + \cdots + a_1 z + a_0} = \bar{0} = 0. \end{aligned}$$

Theorem: The complex eigenvalues of a **real** matrix come in conjugate pairs.

Complex matrices

A complex matrix might have real or complex eigenvalues, and the complex eigenvalues do not have to come in conjugate pairs.

Examples: $\begin{bmatrix} 1 & 2 \\ 0 & i \end{bmatrix}, \begin{bmatrix} 1 & i \\ 0 & 2 \end{bmatrix}.$

General case

In general, don't forget that the quadratic formula

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

gives the roots of $ax^2 + bx + c$, and these can be real (if $b^2 - 4ac \geq 0$) or complex (if $b^2 - 4ac < 0$). This formula also works if a , b and c are complex.

Also don't forget to try small integers first.

Example: Find the real and complex eigenvalues of $A = \begin{bmatrix} 2 & 3 & 0 \\ 1 & 2 & 2 \\ 0 & -2 & 1 \end{bmatrix}.$

Solution:

$$\begin{aligned}
\begin{vmatrix} 2-\lambda & 3 & 0 \\ 1 & 2-\lambda & 2 \\ 0 & -2 & 1-\lambda \end{vmatrix} &= (2-\lambda) \begin{vmatrix} 2-\lambda & 2 \\ -2 & 1-\lambda \end{vmatrix} - 3 \begin{vmatrix} 1 & 2 \\ 0 & 1-\lambda \end{vmatrix} \\
&= (2-\lambda)(\lambda^2 - 3\lambda + 6) - 3(1-\lambda) \\
&= -\lambda^3 + 5\lambda^2 - 9\lambda + 9.
\end{aligned}$$

By trial and error, $\lambda = 3$ is a root. So we factor:

$$-\lambda^3 + 5\lambda^2 - 9\lambda + 9 = (\lambda - 3)(-\lambda^2 + 2\lambda - 3)$$

We don't find any obvious roots for the quadratic factor, so we use the quadratic formula:

$$\begin{aligned}
\lambda &= \frac{-2 \pm \sqrt{2^2 - 4(-1)(-3)}}{-2} = \frac{-2 \pm \sqrt{-8}}{-2} \\
&= \frac{-2 \pm 2\sqrt{2}i}{-2} = 1 \pm \sqrt{2}i.
\end{aligned}$$

So the eigenvalues are 3 , $1 + \sqrt{2}i$ and $1 - \sqrt{2}i$. The algebraic multiplicities are all 1, and $1 + 1 + 1 = 3$.

Note: Our questions always involve real eigenvalues and real eigenvectors unless we say otherwise. But there **will** be problems where we ask for complex eigenvalues.

Section 4.4: Similarity and Diagonalization

We're going to introduce a new concept that will turn out to be closely related to eigenvalues and eigenvectors.

Definition: Let A and B be $n \times n$ matrices. We say that A is **similar** to B if there is an invertible matrix P such that $P^{-1}AP = B$. When this is the case, we write $A \sim B$.

It is equivalent to say that $AP = PB$ or $A = PBP^{-1}$.

Example 4.22: Let $A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & 0 \\ -2 & -1 \end{bmatrix}$. Then $A \sim B$, since

$$\begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -2 & -1 \end{bmatrix}.$$

We also need to check that the matrix $P = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$ is invertible, which is the case since its determinant is 2.

It is tricky in general to find such a P when it exists. We'll learn a method that works in a certain situation in this section.