

# Math 1600 Lecture 6, Section 2, 17 Sep 2014

## Announcements:

**Read** Sections 2.0 and 2.1 for next class. Work through recommended [homework questions](#).

**Quiz** today and tomorrow in lab, covering 1.1, 1.2 and the code vectors part of 1.4.

**Office hour:** today, 11:30-noon, MC103B.

**Help Centers:** Monday-Friday 2:30-6:30 in MC 106 starting today (Sept 17).

**Lecture notes** (this page) available from [course web page](#).

## Partial review of [last lecture](#):

### Section 1.3: Lines and planes in $\mathbb{R}^2$ and $\mathbb{R}^3$

#### Lines in $\mathbb{R}^2$ and $\mathbb{R}^3$

The **vector form** of the equation for a line  $\ell$  is:

$$\vec{x} = \vec{p} + t\vec{d},$$

where  $\vec{p}$  is the position vector of a chosen point on the line,  $\vec{d}$  is a vector parallel to the line, and  $t \in \mathbb{R}$ .

If we expand the vector form into components, we get the **parametric form** of the equations for  $\ell$ :

$$\begin{aligned}x &= p_1 + td_1 \\y &= p_2 + td_2 \\(z &= p_3 + td_3 \quad \text{if we are in } \mathbb{R}^3)\end{aligned}$$

## Lines in $\mathbb{R}^2$

For a line in  $\mathbb{R}^2$ , there are additional ways to describe a line.

The **normal form** of the equation for  $\ell$  is:

$$\vec{n} \cdot (\vec{x} - \vec{p}) = 0 \quad \text{or} \quad \vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p},$$

where  $\vec{n}$  is a vector that is *normal* = *perpendicular* to  $\ell$ .

If we write this out in components, with  $\vec{n} = [a, b]$ , we get the **general form** of the equation for  $\ell$ :

$$ax + by = c,$$

where  $c = \vec{n} \cdot \vec{p}$ . When  $b \neq 0$ , this can be rewritten as  $y = mx + k$ , where  $m = -a/b$  and  $k = c/b$ .

**Note:** All of these simplify when the line goes through the origin, as then you can take  $\vec{p} = \vec{0}$ .

**Note:** None of these equations is *unique*, as  $\vec{p}$ ,  $\vec{d}$  and  $\vec{n}$  can all change. The general form is closest to being unique: it is unique up to an overall scale factor.

## Lines in $\mathbb{R}^3$

There are also **normal** and **general forms** of equations for a line in  $\mathbb{R}^3$ , which I won't review here.

## Planes in $\mathbb{R}^3$

**Normal form:**

$$\vec{n} \cdot (\vec{x} - \vec{p}) = 0 \quad \text{or} \quad \vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p}.$$

When expanded into components, it gives the **general form**:

$$ax + by + cz = d,$$

where  $\vec{n} = [a, b, c]$  and  $d = \vec{n} \cdot \vec{p}$ .

**New material**

**Note:** You can read off  $\vec{n}$  from the general form. Two planes are parallel if and only if their normal vectors are parallel.

A plane can also be described in **vector form**. You need to specify a point  $\vec{p}$  in the plane as well as two vectors  $\vec{u}$  and  $\vec{v}$  which are parallel to the plane but not parallel to each other.

$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}$$

When expanded into components, this gives the **parametric equations** for a plane:

$$x = p_1 + su_1 + tv_1$$

$$y = p_2 + su_2 + tv_2$$

$$z = p_3 + su_3 + tv_3.$$

Table 1.3 in the text summarizes this nicely (except for the one typo mentioned earlier).

It may seem like there are lots of different forms, but really there are two: vector and normal, and these can be expanded into components to give the parametric and general forms.

**Example:** Find all four forms of the equations for the plane in  $\mathbb{R}^3$  which goes through the point  $P = (1, 2, 0)$  and has normal vector

$$\vec{n} = [2, 1, -1].$$

**Solution:** For  $\vec{p} = [1, 2, 0]$  and  $\vec{n} = [2, 1, -1]$ , we have  $\vec{n} \cdot \vec{p} = 4$ . So the normal form is

$$\vec{n} \cdot \vec{x} = 4.$$

The general form is

$$2x + y - z = 4.$$

To get the vector form, we need two vectors parallel to the plane, so we need two vectors perpendicular to  $\vec{n}$ . Can get these by trial and error, for example,  $\vec{u} = [-1, 2, 0]$  and  $\vec{v} = [0, 1, 1]$ . Then the vector form is

$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}.$$

Expanding into components gives the parametric form:

$$x = 1 - s$$

$$y = 2 + 2s + t$$

$$z = t.$$

You can also find parallel vectors by finding two other points  $Q$  and  $R$  in the plane and then taking  $\vec{u} = \vec{PQ}$  and  $\vec{v} = \vec{PR}$ . If  $\vec{u}$  and  $\vec{v}$  are parallel, you need to try again.

**True/false:** The planes given by

$$2x + 3y + 4z = 7$$

and

$$4x + 6y + 8z = 9$$

are parallel.

**True**, because the normal vectors are  $[2, 3, 4]$  and  $[4, 6, 8]$ , which are

parallel.

If the 9 was changed to 14, the two planes would be **equal**, but the answer would still be **true**, as a plane is parallel to itself. The right hand side shifts the position of a plane, but not its orientation.

**True/false:** The lines given by

$$\begin{aligned}\vec{x} &= \vec{p}_1 + t\vec{d}_1, & \vec{p}_1 &= [1, 2, 3], & \vec{d}_1 &= [2, 0, -2] \\ \vec{x} &= \vec{p}_2 + t\vec{d}_2, & \vec{p}_2 &= [2, 4, 6], & \vec{d}_2 &= [2, 1, 0]\end{aligned}$$

are parallel.

**False**, because the direction vectors are  $[2, 0, -2]$  and  $[2, 1, 0]$ , which are not parallel. ( $\vec{p}$  does not matter for this.)

**Example:** Find all four forms of the equations for the plane in  $\mathbb{R}^3$  which goes through the points  $P = (1, 1, 0)$ ,  $Q = (0, 1, 2)$  and  $R = (-1, 2, 1)$ . Solution on board.

## Cross products (Exploration after Section 1.3)

Given vectors  $\vec{u}$  and  $\vec{v}$  in  $\mathbb{R}^3$ , we would like a way to produce a new vector that is orthogonal to both  $\vec{u}$  and  $\vec{v}$ . The **cross product** does this.

**Definition:** The **cross product** of  $\vec{u}$  and  $\vec{v}$  is the vector

$$\vec{u} \times \vec{v} := [u_2v_3 - u_3v_2, u_3v_1 - u_1v_3, u_1v_2 - u_2v_1].$$

**Theorem:**  $\vec{u} \times \vec{v}$  is orthogonal to both  $\vec{u}$  and  $\vec{v}$ . That is,  $\vec{u} \cdot (\vec{u} \times \vec{v}) = 0$  and  $\vec{v} \cdot (\vec{u} \times \vec{v}) = 0$ .

Explain on board.

**Note:** The cross product only makes sense in  $\mathbb{R}^3$ !

Can now finish the previous example, on board.

**Theorem:** The cross product also has the following properties:

$$(a) \vec{v} \times \vec{u} = -(\vec{u} \times \vec{v}) \quad !$$

$$(b) \vec{u} \times \vec{0} = \vec{0}$$

$$(c) \vec{u} \times \vec{u} = \vec{0}$$

$$(d) \vec{u} \times k\vec{v} = k(\vec{u} \times \vec{v}) = (k\vec{u}) \times \vec{v}$$

$$(e) \vec{u} \times k\vec{u} = \vec{0}$$

$$(f) \vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$$

This is exercise 5 from the cross product exploration, and I encourage you to check these properties.

### Distance from a point to a line (back to Section 1.3)

Recall the formula for **the projection of  $\vec{v}$  onto  $\vec{u}$** :

$$\text{proj}_{\vec{u}}(\vec{v}) = \left( \frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \right) \vec{u}.$$

**Example:** Find the distance from the point  $B = (1, 3, 6)$  to the line through  $P = (1, 1, 0)$  in the direction  $\vec{d} = [0, -1, 1]$ . Solution on board, leading to  $d(B, \ell) = \|\vec{v} - \text{proj}_{\vec{d}}(\vec{v})\| = 4\sqrt{2}$ , where  $\vec{v} = \vec{PB}$ .

If the line was in  $\mathbb{R}^2$  and had been described in normal form, one could instead compute  $\|\text{proj}_{\vec{n}}(\vec{v})\|$ , which saves one step.