- 1. For each of the following statements, circle  $T$  if the statement is always true and  $F$  if it can be false. To receive credit, you must give a brief justification for your answer.
- [2] (a) If  $\vec{u}$  and  $\vec{v}$  are orthogonal vectors in  $\mathbb{R}^3$ , then  $\|\vec{u} + \vec{v}\| = \|\vec{u}\| + \|\vec{v}\|$ .

**Solution:** False. For example,  $\vec{u} = [1, 0, 0]$  and  $\vec{v} = [0, 1, 0]$  are orthogonal, but  $\|\vec{u} + \vec{v}\| =$  $\| [1, 1, 0] \| = \sqrt{2}$  and  $\| \vec{u} \| + \| \vec{v} \| = 1 + 1 = 2$ .

(2) If  $\vec{u}$  is orthogonal to both  $\vec{v}$  and  $\vec{w}$ , then  $\vec{u}$  is orthogonal to  $2\vec{v} + 3\vec{w}$ .

**Solution:** True, since  $\vec{u} \cdot (2\vec{v} + 3\vec{w}) = 2\vec{u} \cdot \vec{v} + 3\vec{u} \cdot \vec{w} = 2(0) + 3(0) = 0.$ 

[2] (c) If none of vectors  $\vec{u}, \vec{v}, \vec{w}$  in  $\mathbb{R}^3$  is a scalar multiple of one of the others, then the set  $S = {\vec{u}, \vec{v}, \vec{w}}$  is linearly independent.

**Solution:** False. Consider the vectors  $[1, 0, 0]$ ,  $[0, 1, 0]$  and  $[1, 1, 0]$ .

(d)[2] Every system of 3 linear equations in 4 unknowns has infinitely many solutions.

**Solution:** False. For example, if  $x + y + w + z = 0$  and  $x + y + w + z = 1$  are two of the linear equations, then the system has no solutions.

[2] (e) Let 
$$
\vec{u} = [3, 6]
$$
 and  $\vec{v} = [2, 4]$ . Then span $(\vec{u}, \vec{v}) = \mathbb{R}^2$ .

Solution: False, since they are parallel and therefore span a line.

[2] (f) Let A be a 
$$
2 \times 2
$$
 matrix. If  $B = A^2$ , then  $AB = BA$ .

**Solution:** True, since  $AB = A(A^2) = A^3$  and  $BA = (A^2)A = A^3$ .

[2] (g) A matrix of the form  $\begin{bmatrix} a & 1 \\ 1 & a \end{bmatrix}$  $-1$  a 1 is invertible, for all real numbers a.

**Solution:** True. Its determinant is  $a^2 + 1 \ge 1 > 0$ , so it is invertible.

[2] (h) The set  $S = \{ [x, y, z] \in \mathbb{R}^3 \mid y = x^2 \}$  is a subspace of  $\mathbb{R}^3$ .

**Solution:** False. For example,  $[1, 1, 0]$  is in S (since  $1^2 = 1$ ), but  $2[1, 1, 0] = [2, 2, 0]$  is not in S (since  $2^2 \neq 2$ ).

- 2. Let  $\vec{u} = [2, -1, 3]$  and  $\vec{v} = [3, 2, 1].$
- [3] (a) Find the angle between  $\vec{u}$  and  $\vec{v}$ .

Solution: We have

$$
\cos \theta = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} = \frac{7}{\sqrt{14}\sqrt{14}} = \frac{7}{14} = \frac{1}{2}
$$

and so  $\theta = 60$  degrees.

[2] (b) Compute the projection  $proj_{\vec{u}}(\vec{v})$  of  $\vec{v}$  onto  $\vec{u}$ . Solution:

proj<sub>$$
\vec{u}
$$</sub>( $\vec{v}$ ) =  $\frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}}$  $\vec{u} = \frac{7}{14} [2, -1, 3] = [1, -1/2, 3/2].$ 

[4] 3. Let V be the plane in  $\mathbb{R}^3$  given by  $2x + y - z = 0$ , and let W be the line in  $\mathbb{R}^3$  through the origin in the direction of [1, 0, 1]. Find vectors  $\vec{v} \in V$  and  $\vec{w} \in W$  such that  $\vec{v} + \vec{w} = [1, 1, 1]$ . (Hint: you know  $\vec{w} = t[1, 0, 1]$  for some scalar t.)

**Solution:** Let  $\vec{w} = t[1, 0, 1]$ . Then  $\vec{v} = [1, 1, 1] - t[1, 0, 1] = [1 - t, 1, 1 - t]$ . Since  $\vec{v}$  is in the plane, we must have  $2(1-t)+1-(1-t) = 0$ . That is,  $-t+2 = 0$ , and so  $t = 2$ . So  $\vec{w} = 2[1, 0, 1] = [2, 0, 2]$ and  $\vec{v} = [1, 1, 1] - [2, 0, 2] = [-1, 1, -1].$ 

[4] 4. (a) Find a normal vector for the equation of a plane that contains the two lines  $\vec{x} = \vec{p} + s\vec{u}$  and  $\vec{x} = \vec{p} + t\vec{v}$ , where

 $\vec{p} =$  $\sqrt{ }$  $\overline{1}$ 1 0 2 1  $\Big\vert \ ,\quad \vec u =$  $\sqrt{ }$  $\overline{1}$ 3 1  $\overline{0}$ 1  $\Big\}, \quad \text{and} \quad \vec{v} =$  $\sqrt{ }$  $\overline{1}$ −1 1 1 1  $\vert \cdot$ 

**Solution:** Since the plane contains the two lines, it goes through the point  $\vec{p}$  and has  $\vec{u}$  and  $\vec{v}$  as direction vectors. (They are not parallel.)

We take the cross product of the direction vectors to find a normal vector:

$$
\vec{u} \times \vec{v} = \begin{bmatrix} 1 \\ -3 \\ 4 \end{bmatrix}.
$$

[3] (b) Find a general equation for the plane in part (a).

**Solution:** Using (a), we know the equation is of the form  $x - 3y + 4z = d$ . We plug in the point  $(1, 0, 2)$  to find that  $d = 9$ , so the equation is

$$
x - 3y + 4z = 9.
$$

[4] 5. Consider a code that uses code words in  $\mathbb{Z}_5^6$  and has check vector  $\vec{c} = [2, 1, 2, 1, 2, 1]$ . Find the digit d in  $\mathbb{Z}_5$  that makes  $\vec{v} = [3, 1, 2, 3, 2, d]$  into a valid code word.

## Solution: We compute

$$
\vec{c} \cdot \vec{v} = 2(3) + 1(1) + 2(2) + 1(3) + 2(2) + 1(d) = 6 + 1 + 4 + 3 + 4 + d = 18 + d = 3 + d
$$

in  $\mathbb{Z}_5$ . To make this 0, we choose  $d = 2$ .

[5] 6. Determine the currents in this electrical network.

Solution: Kirchhoff's current law at node A gives:

$$
I_1 - I_2 + I_3 = 0.
$$

At node B, you get the same equation.

Kirchhoff's voltage law for the bottom loop gives:

$$
2I_2 + 4I_3 = 8.
$$

And for the top loop we get:

$$
I_1 + 2I_2 = 5.
$$

So we need to solve the system whose augmented matrix is:



[4] 7. Let A, B and X be invertible  $n \times n$  matrices. Solve the following matrix equation for X in terms of A and B. Show your steps, and simplify your answer.

$$
A^T X + (X^T A)^T = B
$$

Solution:

$$
A^T X + (X^T A)^T = B
$$
  
\n
$$
\implies A^T X + A^T X = B
$$
  
\n
$$
\implies 2A^T X = B
$$
  
\n
$$
\implies X = \frac{1}{2} (A^T)^{-1} B
$$



8. Let 
$$
A = \begin{bmatrix} 2 & 1 & 3 \\ 4 & 2 & 2 \\ -2 & 2 & 3 \end{bmatrix}
$$
.

[4] (a) Determine whether A is invertible, and if so, find  $A^{-1}$ , showing your work. **Solution:** Row reducing  $[A|I]$  leads to

$$
\left[\begin{array}{ccc|ccc|ccc} 1 & 0 & 0 & 1/12 & 1/8 & -1/6 \\ 0 & 1 & 0 & -2/3 & 1/2 & 1/3 \\ 0 & 0 & 1 & 1/2 & -1/4 & 0 \end{array}\right]
$$

and so  $A$  is invertible with inverse

$$
\left[\begin{array}{ccc} 1/12 & 1/8 & -1/6 \\ -2/3 & 1/2 & 1/3 \\ 1/2 & -1/4 & 0 \end{array}\right]
$$

[3] (b) Using your answer to part (a), determine whether the system  $A\vec{x} = \vec{0}$  has a unique solution.

Solution: By the fundamental theorem of invertible matrices, it does have a unique solution since  $A$  is invertible.

Alternatively, by the above work, we see that there will be no free variables.

9. Let

$$
A = \begin{bmatrix} 1 & 3 & 0 & 5 & 0 & 4 \\ 2 & 6 & 1 & 8 & 0 & 5 \\ 2 & 6 & 2 & 6 & 1 & 9 \end{bmatrix} \text{ and } R = \begin{bmatrix} 1 & 3 & 0 & 5 & 0 & 4 \\ 0 & 0 & 1 & -2 & 0 & -3 \\ 0 & 0 & 0 & 0 & 1 & 7 \end{bmatrix}.
$$

Given that  $R$  is the reduced row-echelon form of  $A$ , compute each of the following. Explain briefly.

## [1] (a) rank $(A)$ .

Solution: The rank is 3, since the row echelon form R has three non-zero rows.

[2] (b) A basis for row(A).

**Solution:** A basis for the row space of A is given by the non-zero rows of  $R$ :

 $[1, 3, 0, 5, 0, 4], [0, 0, 1, -2, 0, -3]$  and  $[0, 0, 0, 0, 1, 7]$ 

[2] (c) A basis for  $col(A)$ .

**Solution:** A basis for the column space of A is given by the columns of A that correspond to columns of  $R$  with leading 1's:



## [3] (d) A basis for  $null(A)$ .

**Solution:** From the matrix  $R$  we get the equations

$$
x_1 + 3x_2 + 5x_4 + 4x_6 = 0
$$
,  $x_3 - 2x_4 - 3x_6 = 0$  and  $x_5 + 7x_6 = 0$ 

The variables  $x_2 = r$ ,  $x_4 = s$  and  $x_6 = t$  are free, and the equations above give formulas for  $x_1, x_3$  and  $x_5$ , so we find the general solution to be

$$
\vec{x} = r \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} -5 \\ 0 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -4 \\ 0 \\ 3 \\ 0 \\ -7 \\ 1 \end{bmatrix},
$$

so a basis for the null space is given by the three vectors shown.

- 10. Let A be a square matrix.
- [2] (a) Assume that A is invertible. Show that  $A^T A$  is invertible by finding a formula for  $(A^T A)^{-1}$ in terms of  $A^{-1}$ .

**Solution:** Recall that, if A is invertible, then  $(A^T)^{-1} = (A^{-1})^T$ . Also, if A and B are both invertible of the same size, then  $(AB)^{-1} = B^{-1}A^{-1}$ . Thus,  $(A^T A)^{-1} = A^{-1} (A^{-1})^T$  exists.

[2] (b) Now assume that  $A^T A$  is invertible. Show that A is invertible by showing that  $(A^T A)^{-1} A^T$ is an inverse to A.

> **Solution:** Since A is square, it is enough to show that  $(A^T A)^{-1} A^T$  is a one-sided inverse to A, and this is easy to check:

$$
((A^T A)^{-1} A^T) A = (A^T A)^{-1} (A^T A) = I.
$$

Note that it is *not* valid to write  $(A^T A)^{-1} = A^{-1} (A^T)^{-1}$  until we show that A is invertible.

[5] 11. Are the vectors 
$$
\vec{u}_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}
$$
,  $\vec{u}_2 = \begin{bmatrix} 0 \\ 2 \\ 3 \end{bmatrix}$ ,  $\vec{u}_3 = \begin{bmatrix} 3 \\ 8 \\ 5 \end{bmatrix}$ , and  $\vec{u}_4 = \begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix}$  linearly dependent? If so, find scalars  $c_1$ ,  $c_2$ ,  $c_3$  and  $c_4$  such that  $c_1\vec{u}_1 + c_2\vec{u}_2 + c_3\vec{u}_3 + c_4\vec{u}_4 = \vec{0}$ .

**Solution:** A collection of four vectors in  $\mathbb{R}^3$  is always linearly dependent. To find the dependency relationship, we have to solve the system



Row re

$$
c_1 = -5t, c_2 = -3t, c_3 = 2t, c_4 = t.
$$

Picking  $t = 1$  gives a specific relationship

$$
-5\vec{u}_1 - 3\vec{u}_2 + 2\vec{u}_3 + \vec{u}_4 = \vec{0}.
$$