

Math 1600B Lecture 6, Section 2, 17 Jan 2014

Announcements:

Read Sections 2.0 and 2.1 for next class. Work through recommended [homework questions](#).

The next quiz will be next week, and will cover the material until the end of Monday's class

Help Centers Monday-Friday 2:30-6:30 in MC 106 start on Monday, January 20.

Lecture notes (this page) available from [course web page](#).

Partial review of last lecture:

Section 1.3: Lines and planes in \mathbb{R}^2 and \mathbb{R}^3

Lines in \mathbb{R}^2 and \mathbb{R}^3

The **vector form** of the equation for a line ℓ is:

$$\vec{x} = \vec{p} + t\vec{d},$$

where \vec{p} is the position vector of a chosen point on the line, \vec{d} is a vector parallel to the line, and $t \in \mathbb{R}$.

If we expand the vector form into components, we get the **parametric form** of the equations for ℓ :

$$\begin{aligned} x &= p_1 + td_1 \\ y &= p_2 + td_2 \\ (z &= p_3 + td_3 \quad \text{if we are in } \mathbb{R}^3) \end{aligned}$$

Lines in \mathbb{R}^2

For a line in \mathbb{R}^2 , there are additional ways to describe a line.

The **normal form** of the equation for ℓ is:

$$\vec{n} \cdot (\vec{x} - \vec{p}) = 0 \quad \text{or} \quad \vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p},$$

where \vec{n} is a vector that is *normal* = *perpendicular* to ℓ .

If we write this out in components, with $\vec{n} = [a, b]$, we get the **general form** of the equation for ℓ :

$$ax + by = c,$$

where $c = \vec{n} \cdot \vec{p}$. When $b \neq 0$, this can be rewritten as $y = mx + k$, where $m = -a/b$ and $k = c/b$.

Note: All of these simplify when the line goes through the origin, as then you can take $\vec{p} = \vec{0}$.

Note: None of these equations is *unique*, as \vec{p} , \vec{d} and \vec{n} can all change. The general form is closest to being unique: it is unique up to an overall scale factor.

Lines in \mathbb{R}^3

There are also **normal** and **general forms** of equations for a line in \mathbb{R}^3 , which I won't review here.

Planes in \mathbb{R}^3

Normal form:

$$\vec{n} \cdot (\vec{x} - \vec{p}) = 0 \quad \text{or} \quad \vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p}.$$

When expanded into components, it gives the **general form**:

$$ax + by + cz = d,$$

where $\vec{n} = [a, b, c]$ and $d = \vec{n} \cdot \vec{p}$.

Vector form: You need to specify a point \vec{p} in the plane as well as *two* vectors \vec{u} and \vec{v} which are parallel to the plane but not parallel to each other.

$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}$$

When expanded into components, this gives the **parametric equations** for a plane:

$$\begin{aligned}x &= p_1 + su_1 + tv_1 \\y &= p_2 + su_2 + tv_2 \\z &= p_3 + su_3 + tv_3.\end{aligned}$$

Table 1.3 in the text summarizes this material nicely.

It may seem like there are lots of different forms, but really there are two: vector and normal, and these can be expanded into components to give the parametric and general forms.

New material

Example: Find all four forms of the equations for the plane in \mathbb{R}^3 which goes through the points $P = (1, 1, 0)$, $Q = (0, 1, 2)$ and $R = (-1, 2, 1)$. Solution on board.

But we get stuck on the normal form, which motivates:

Cross products (Exploration after Section 1.3)

Given vectors \vec{u} and \vec{v} in \mathbb{R}^3 , we would like a way to produce a new vector that is orthogonal to both \vec{u} and \vec{v} . The **cross product** does this.

Definition: The **cross product** of \vec{u} and \vec{v} is the vector

$$\vec{u} \times \vec{v} := [u_2v_3 - u_3v_2, u_3v_1 - u_1v_3, u_1v_2 - u_2v_1].$$

Theorem: $\vec{u} \times \vec{v}$ is orthogonal to both \vec{u} and \vec{v} . That is, $\vec{u} \cdot (\vec{u} \times \vec{v}) = 0$ and $\vec{v} \cdot (\vec{u} \times \vec{v}) = 0$.

Explain on board.

Note: The cross product only makes sense in \mathbb{R}^3 !

Can now finish the previous example, on board.

Theorem: The cross product also has the following properties:

- (a) $\vec{v} \times \vec{u} = -(\vec{u} \times \vec{v})$!
- (b) $\vec{u} \times \vec{0} = \vec{0}$
- (c) $\vec{u} \times \vec{u} = \vec{0}$
- (d) $\vec{u} \times k\vec{v} = k(\vec{u} \times \vec{v}) = (k\vec{u}) \times \vec{v}$
- (e) $\vec{u} \times k\vec{u} = \vec{0}$
- (f) $\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$

This is exercise 5 from the cross product exploration, and I encourage you to check these properties.

Distance from a point to a line (back to Section 1.3)

Recall the formula for **the projection of \vec{v} onto \vec{u}** :

$$\text{proj}_{\vec{u}}(\vec{v}) = \left(\frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \right) \vec{u}.$$

Example: Find the distance from the point $B = (1, 3, 6)$ to the line through $P = (1, 1, 0)$ in the direction $\vec{d} = [0, -1, 1]$. Solution on board, leading to $d(B, \ell) = \|\vec{v} - \text{proj}_{\vec{d}}(\vec{v})\| = 4\sqrt{2}$, where $\vec{v} = \vec{PB}$.

If the line was in \mathbb{R}^2 and had been described in normal form, one could instead compute $\|\text{proj}_{\vec{n}}(\vec{v})\|$, which saves one step.

Distance from a point to a plane

Example: Find the distance from the point $B = (1, 3, 6)$ to the plane \mathcal{P} whose equation is $2x + y - z = 2$. Solution on board, leading to

$$d(B, \mathcal{P}) = \|\text{proj}_{\vec{n}}(\vec{v})\| = \frac{|\vec{n} \cdot \vec{v}|}{\|\vec{n}\|} = |-3|/\sqrt{6} = 3/\sqrt{6}.$$